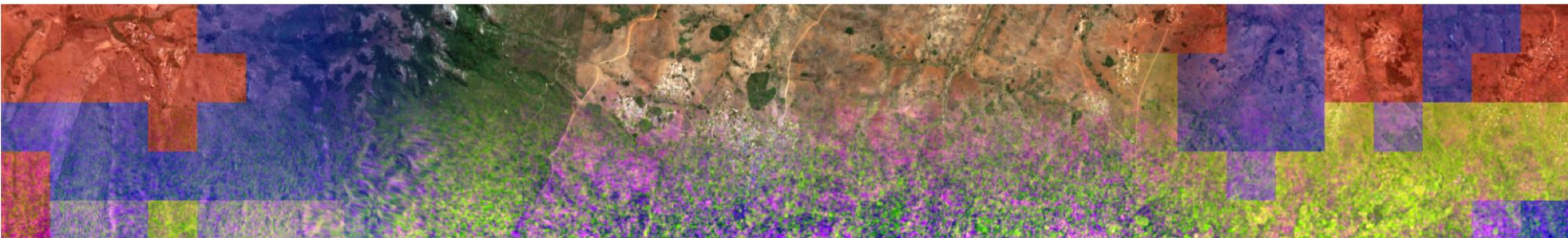
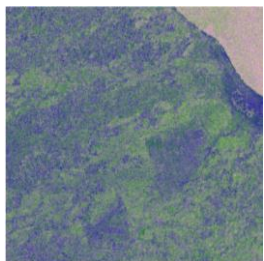


Multi-Branch Deep Learning model for detection of settlements without electricity

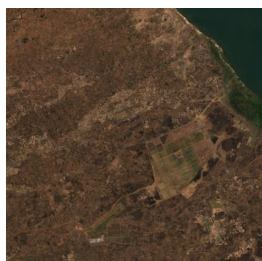
Thomas Di Martino, Maxime Lenormand, Élise Colin Koeniguer



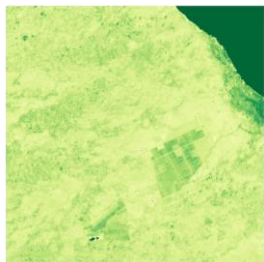
Data – Satellite Imagery



S1
(VV, VH, VV-
VH)



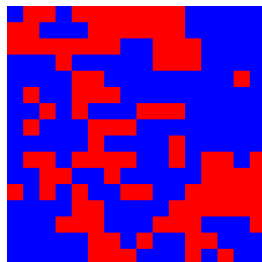
S2
(B04, B03, B02)



S2
(B08-B04)/(B08+B04)
"RdYIGn" Color Scale



VIIRS
(DNB)

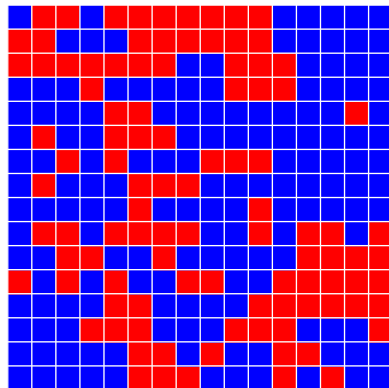


Prediction Map
(Red: Human settlements without electricity,
Blue: No human settlements without
electricity)

60 images of 800x800 pixels combining multimodality & multi-temporality:





- Sentinel 1: **4 acquisitions** with **2 bands** each, resolution ~10m (GRD product)
- Sentinel 2: **4 acquisitions** with **12 bands** each, resolution of 10m, 20m & 60m
- Landsat 8: **3 acquisitions** with **11 bands** each, resolution of 15m, 30m, & 100m
- VIIRS: VNP46A1 product, for **9 acquisitions**, with the **Day-Night Band** only, resolution of 750m resampled to 500m

Our perception of the dataset

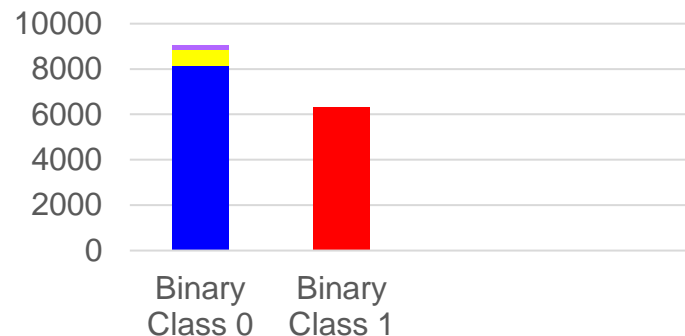






- Each label image consists of a **16x16 matrix of classes upsampled** to match the original dataset resolution of 800x800 pixels.
- We **split** the initial 800x800 images **into 256 50x50** patches, each having a single class value.
- We transform a segmentation task into a classification one.
- We split the new dataset of 15 360 images into 3 folds for cross-validation.

Data – Ground Truth Labels

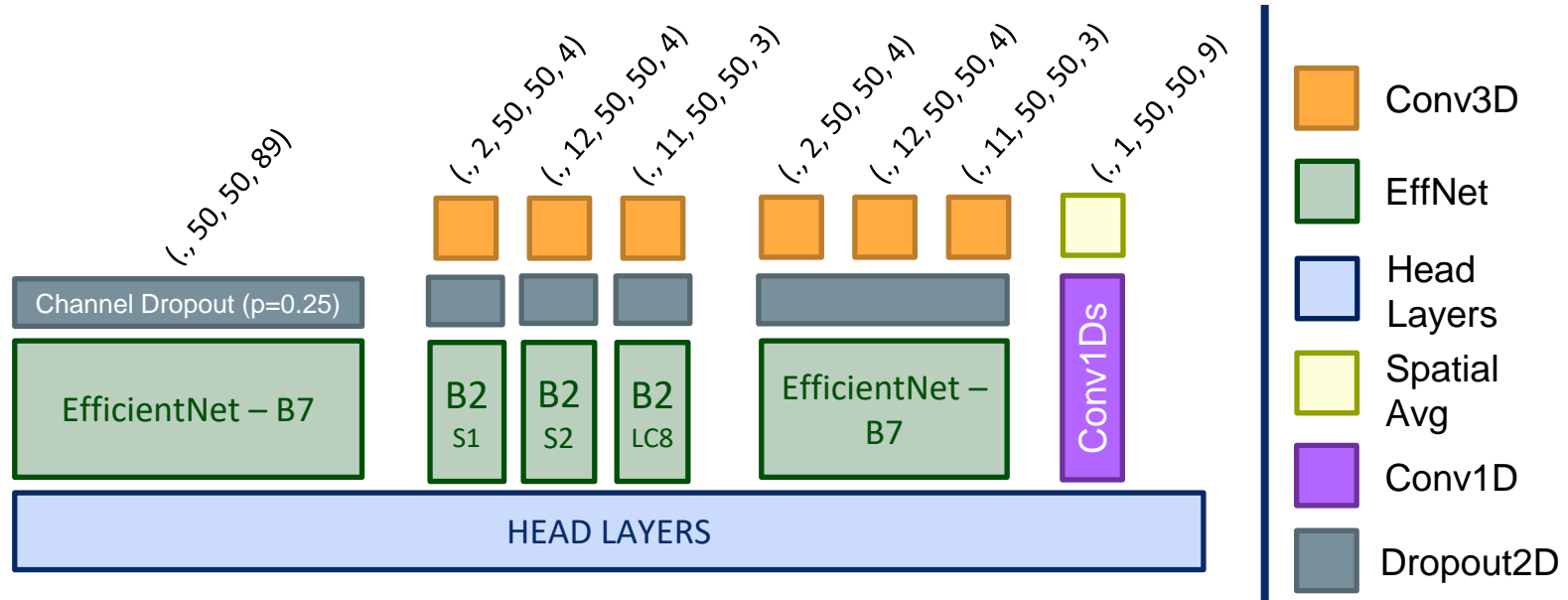
| | With electricity | Without electricity | |
|---------------------|---|---|------|
| With settlements |  676 |  6318 ^(ROI) | 6994 |
| Without settlements |  211 |  8155 | 8366 |
| | 887 | 14473 | |

Classes distribution

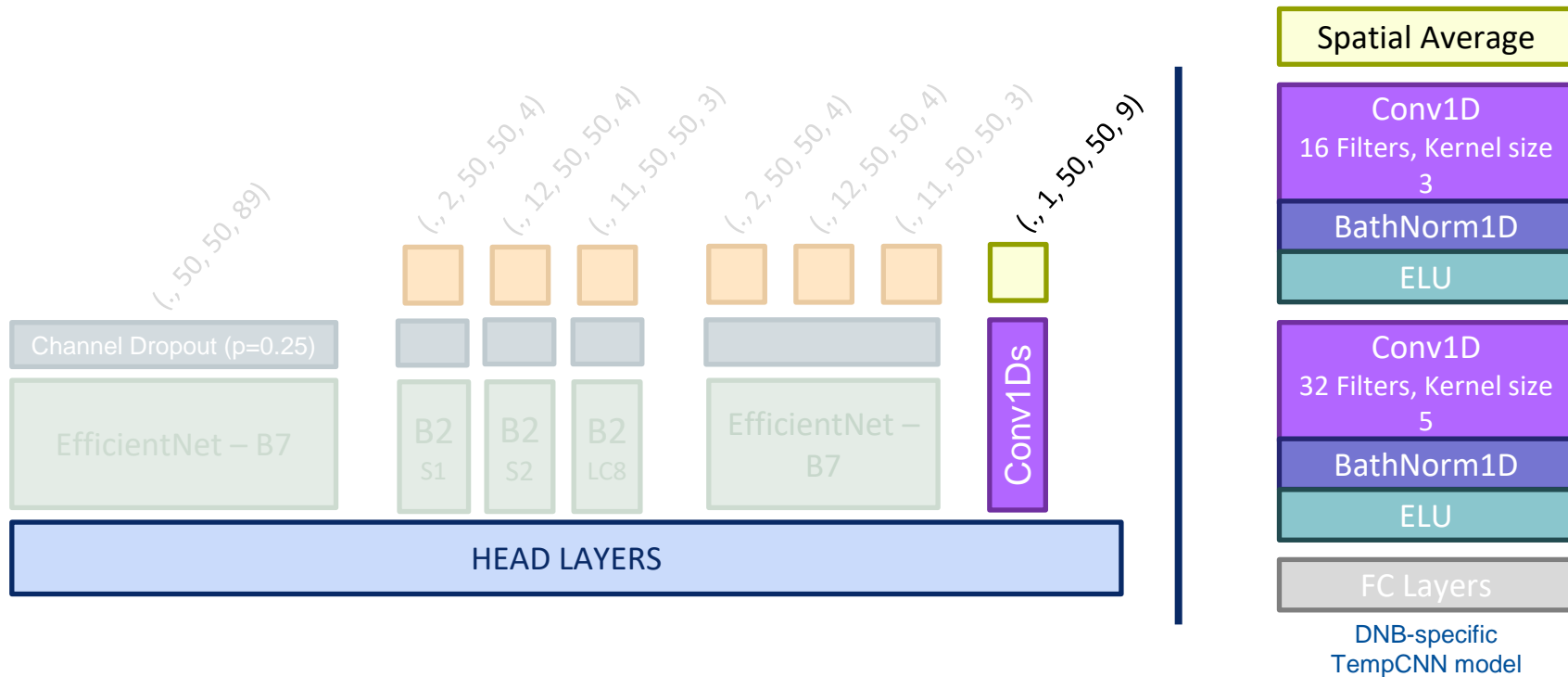


-  No settlements with electricity (4)
-  Settlements with electricity (3)
-  No settlements without electricity(2)
-  Settlements without electricity (1)

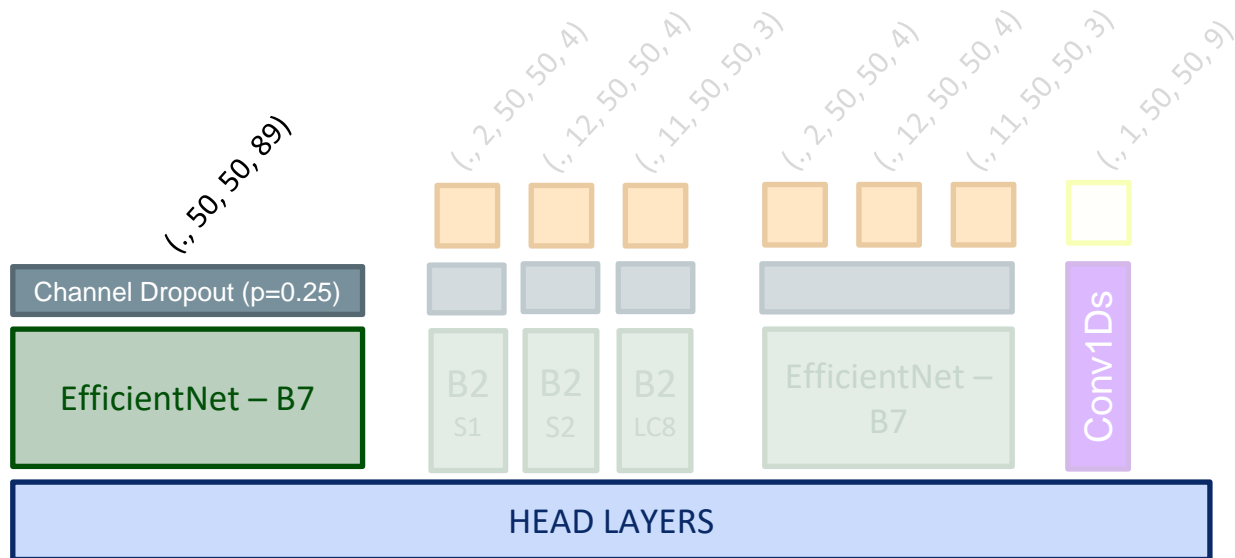
Model Architecture



Model Architecture: Day-Night Band processing branch

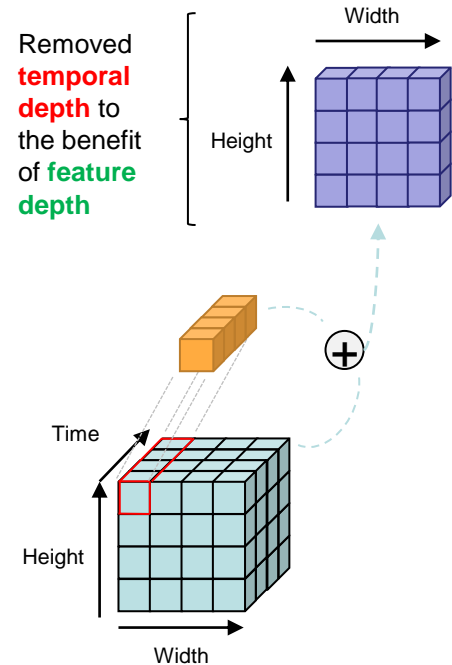
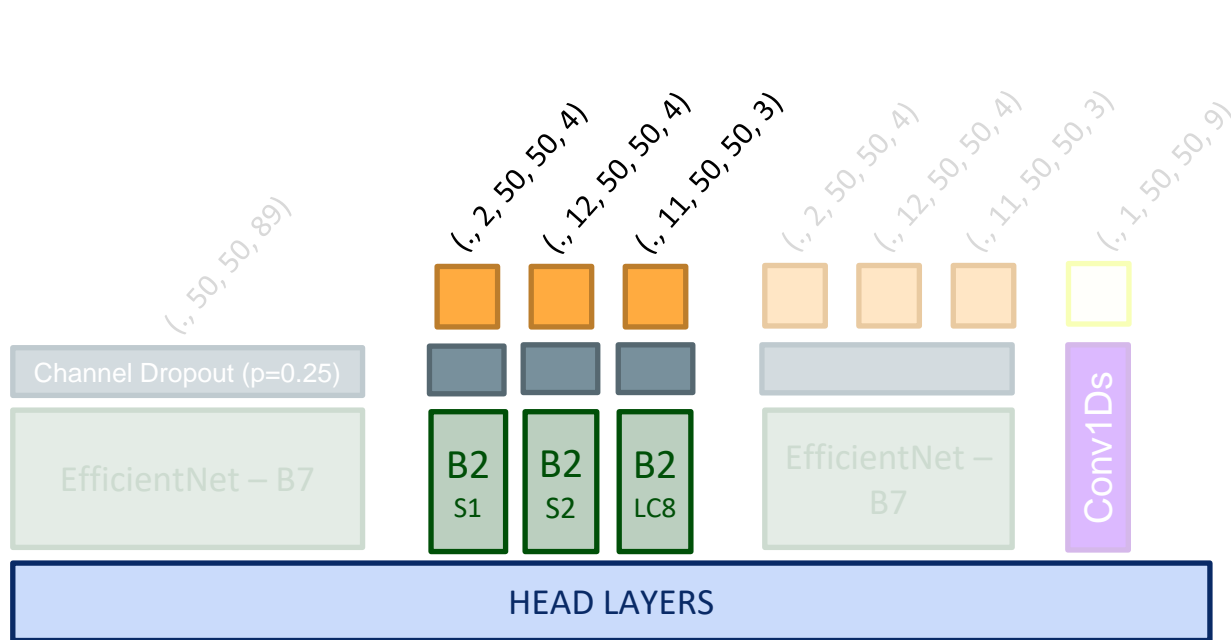


Model Architecture: Multimodal Branch

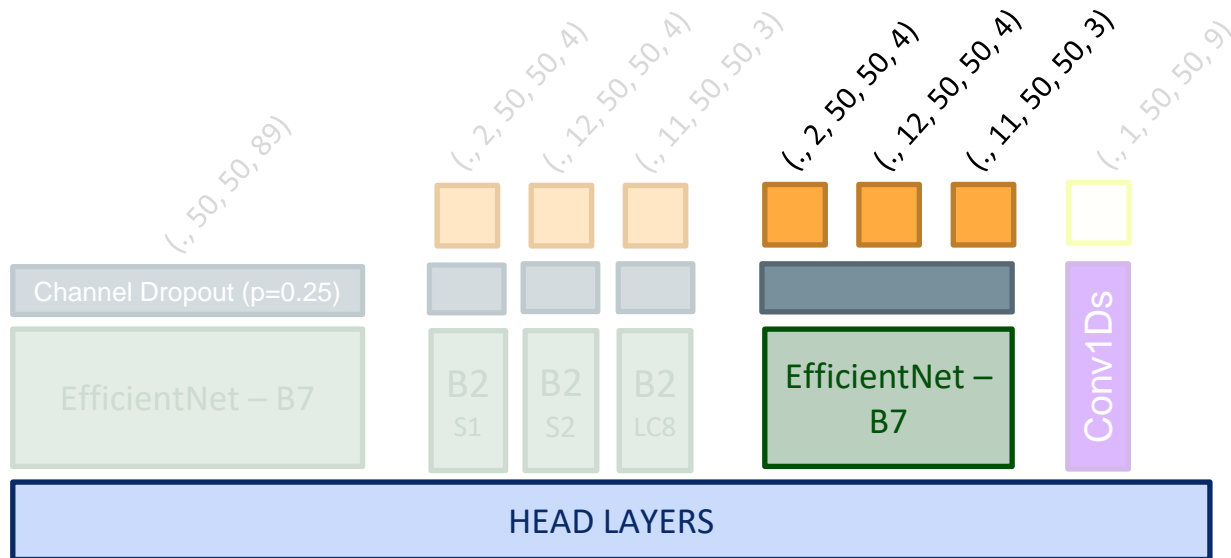


- 89 channels is a lot and can be detrimental to convergence
- Adding channel dropout with a rate of 25% helps for that matter

Model Architecture: MultiUnimodal branch

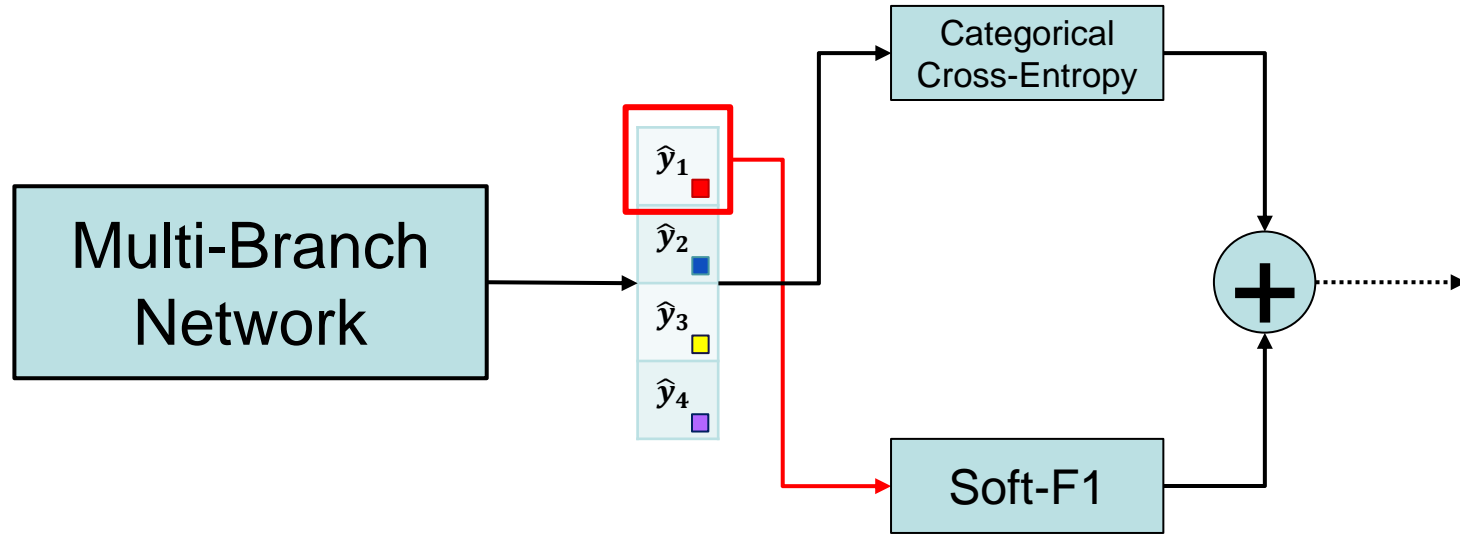


Model Architecture: Temporal-Merged branch



- Separate temporal processing but merged texture feature extraction
- Mix between the Multimodal and the Multi-Unimodal branches

Training setup: Loss calculation



Training setup: Soft-F1 Loss

We define the equations for our Soft-F1 Loss as the following:

$$\left. \begin{aligned} \text{Soft - precision}(\mathbf{y}, \hat{\mathbf{y}}) &= \frac{\sum \hat{\mathbf{y}}_1 * \mathbf{y}_1}{\sum \hat{\mathbf{y}}_1 + \epsilon} \\ \text{Soft - recall}(\mathbf{y}, \hat{\mathbf{y}}) &= \frac{\sum \hat{\mathbf{y}}_1 * \mathbf{y}_1}{\sum \mathbf{y}_1 + \epsilon} \end{aligned} \right\} \text{Soft - F1}(\mathbf{y}, \hat{\mathbf{y}}) = 1 - \frac{2 * sp(\mathbf{y}, \hat{\mathbf{y}}) * sr(\mathbf{y}, \hat{\mathbf{y}}) + \lambda}{sp(\mathbf{y}, \hat{\mathbf{y}}) + sr(\mathbf{y}, \hat{\mathbf{y}}) + \lambda}$$

The two added hyperparameters are the following:

- ϵ is a term used to prevent any division by zero, resulting in a Loss value equal to Nan. It is set to $1e - 5$.
- λ is a term used to smoothen the Soft-F1 loss value. It is set to 0.1.

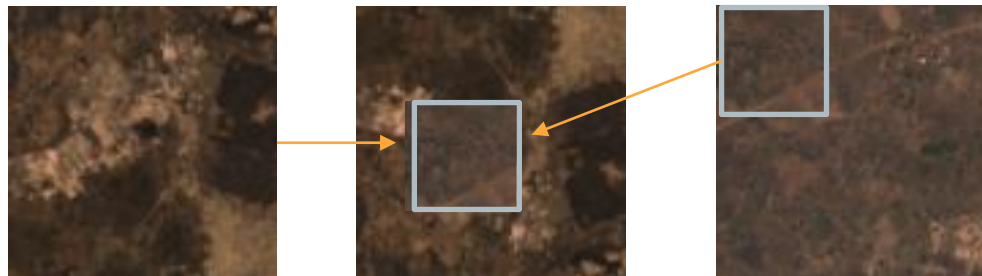
Inspired by: <https://www.kaggle.com/c/planet-understanding-the-amazon-from-space/discussion/34484#191547>

Data Augmentation

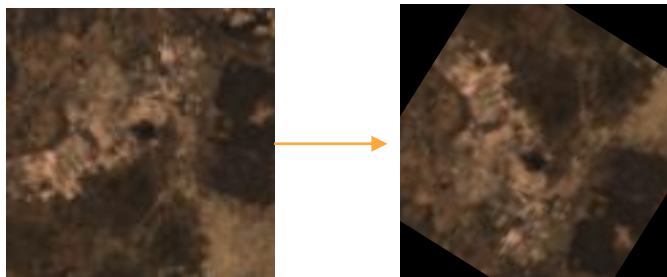
Horizontal/Vertical Flip



CutMix (restricted between same-class images)



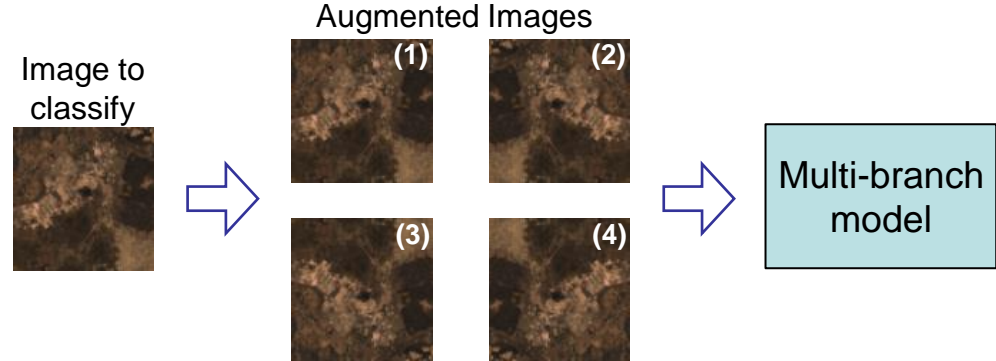
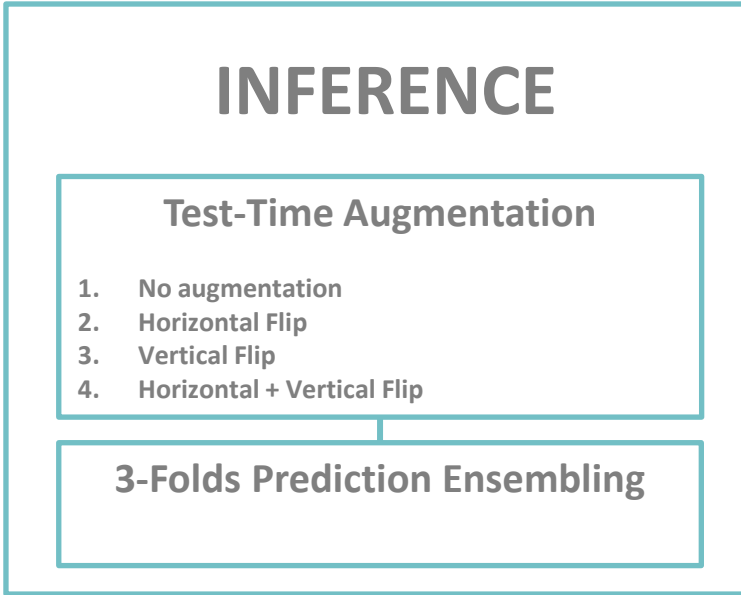
Random Rotation



Noisy Labels (random offset in cropping)



Test-Time Augmentation & Ensembling



$$pred(X) = \begin{cases} 1, & \sum_{aug=1}^4 \sum_{m=1}^3 model_m(f_{aug}(X))_1 > thresh \\ 0, & else \end{cases}$$

Final results

| Fold 1 Val | Fold 2 Val | Fold 3 Val | Dev Phase | Test Phase |
|------------|------------|------------|--------------|--------------|
| 0.8547 | 0.8533 | 0.8722 | 0.8877 (1st) | 0.8798 (3rd) |

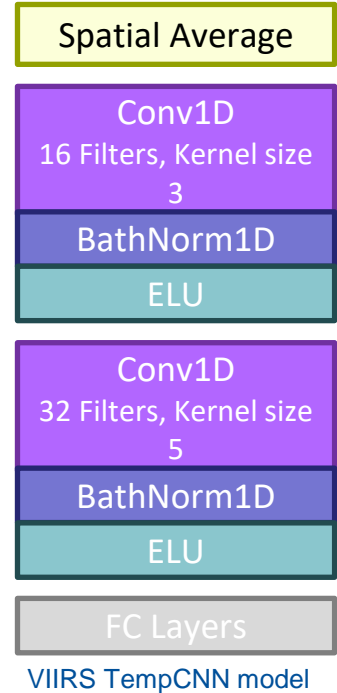
Winning model submission F1 score

Assessing VIIRS ability to detect electrification

- Using a binary version of the dataset with the classes: electrified, not electrified
- Isolation of the DNB-specific branch to train as a separate classifier of electrification

| | |
|------------------|---------------------|
| With electricity | Without electricity |
| 887 | 14473 |

| Subset | Fold 1 | | Fold 2 | | Fold 3 | |
|--------|--------|-------|--------|-------|--------|------|
| | Train | Val | Train | Val | Train | Val |
| VIIRS | 0.712 | 0.718 | 0.765 | 0.462 | 0.674 | 0.75 |



Assessing each sensor ability to detect the class of interest

- Using combinations of VIIRS and each sensor to assess and study their ability to detect *settlements without electricity*

| Sensor Subset | Fold 1 | | Fold 2 | | Fold 3 | |
|--------------------|--------------|--------------|--------------|--------------|--------------|--------------|
| | Train | Val | Train | Val | Train | Val |
| S1, VIIRS | 0.681 | 0.653 | 0.657 | 0.665 | 0.677 | 0.672 |
| LC8, VIIRS | 0.766 | 0.758 | 0.750 | 0.745 | 0.768 | 0.776 |
| S2, VIIRS | 0.834 | 0.817 | 0.822 | 0.824 | 0.850 | 0.859 |
| S1, S2, LC8, VIIRS | 0.893 | 0.854 | 0.900 | 0.853 | 0.878 | 0.872 |

General Conclusion

- Development of a multi-branch architecture, acknowledging the multimodal and multitemporal structure of the data
- Design of a custom training & testing environment (custom loss, data augmentation, TTA & ensembling)
- Experimentations displaying the contribution of each sensor to the final prediction (S2 > LC8 > S1)
- Potential axis of improvements: reflect regarding the type of data to be aggregated & how to combine them in a physically meaningful way (e.g., SAR Time Series & Interferometric products could be of interest)

Acknowledgements

- Thank you to the IEEE GRSS IADF Technical Committee, Hewlett Packard Enterprise, SolarAid & Data Science Experts for organizing this Data Fusion Contest.
- Congrats to all participants for their results and thank you for the exciting *Development phase* and the thrilling and positively stressful *Test Phase*. 😊
- Many thanks to our colleagues at ONERA for their support during the challenge, especially Adrien Chan Hon Tong, Aurélien Plyer and Guy Le Besnerais.
- And many thanks to you for attending this presentation !

Bibliography

- [1] Naoto Yokoya, Pedram Ghamisi, Ronny Hansch, Colin Prieur, Hana Malha, Jocelyn Chanussot, Caleb Robinson, Kolya Malkin, and Nebojsa Jojic, “2021 data fusion contest: Geospatial artificial intelligence for social good [technical committees],” *IEEE Geoscience and Remote Sensing Magazine*, vol. 9, no. 1, pp. 287–C3, 2021.
- [2] Sangdoon Yun, Dongyoon Han, Seong Joon Oh, Sanghyuk Chun, Junsuk Choe, and Youngjoon Yoo, “CutMix: Regularization strategy to train strong classifiers with localizable features,” 2019.